Miniaturized GNSS/Inertial System

### If size and weight matters

**ADMA-Slim** 



# **Range of applications**

- ▲ Motion Tracking for applications with
- size and weight restrictions:
- Vulnerable road users VRU (e.g. pedestrians, bikers)
- Over-runnable platforms
- (e.g. for VRUs and GSTs)
- Motorbikes



### **About ADMA-Slim**

ADMA-Slim is a fullfledged GNSS/Inertial System based on MEMS gyroscopes and accelerometers and a high performance geodetic GNSS receiver. Performance-wise it is comparable to our ADMA-G-EntryLevel or ADMA-Speed models. The ADMA-Slim has been designed for applications with space or weight restrictions, e.g. to be integrated in overrunnable platforms for GSTs (Guided Soft Targets) or VRU (Vulnerable Road User) dummies.

## **Ordering Variants**

ADMA-Slim is available in three different versions:

- ▲ Standard version with 7 LEMO connectors in a waterproof aluminium housing
- ▲ Single connector version with MIL connector in a waterproof aluminium housing
- ▲ Unhoused OEM version

ADMA-Slim is available either with an L1 GNSS receiver with SBAS and DGPS correction data reception capability or with an L1/L2 GNSS receiver with RTK2 correction data reception capability, allowing for position accuracy down to the centimeter.



## **Options**

In addition, the following options are available for ADMA-Slim:

### ▲ OPT-GLONASS / OPT-BEIDOU

Improvement of satellite visibility due to GLONASS or BeiDou reception capability

- ▲ OPT-10g Accelerometers  $\pm 10g$
- ▲ **OPT-15g** Accelerometers  $\pm$  15g
- ▲ OPT-DUAL-ANT: 2 antenna version for course angle without initialization (e.g. low speed applications)

### ▲ OPT-1KHZ:

- 1 kHz data output rate via Ethernet, as opposed to standard 400 Hz
- ▲ OPT-DELTA
- ▲ OPT-BRAKING
- ▲ OPT-ACCELERATE
- ▲ OPT-DGPS
- ▲ OPT-LATDEV
- ▲ OPT-GPS-RAW <sup>9</sup>
- \* Refer to page 6 and 7 for more details



- Sports cars, Jet-Skis, Snow mobiles - ATVs (All Terrain Vehicles)
- ▲ Vehicle dynamics testing with MEMS performance
- ▲ ADAS testing with MEMS performance

# **Scope of Delivery**

- ▲ ADMA-Slim module
- ▲ GPS / GLONASS / Galileo / BeiDou patch antenna
- ▲ Power cable <sup>3</sup>
- ▲ GPS antenna cable \*
- ▲ CAN cable
- ▲ Ethernet cable <sup>></sup>
- ▲ GPS receiver configuration cable \*
- ▲ Documentation, including test protocol and calibration report
- ▲ Software package for configuration and data recording
- ▲ Transport case
- \* not included in OEM version package



## **Technical Data**

### COMPLETE SYSTEM

Angle Measurement range heading / roll / pitch	± 180 / 60 / 60 °	
Angle Measurement accuracy roll & pitch /	0.02 (1 o) /	
heading / sideslip*	0.05 (1 σ) / 0.15 ° RMS	
Angle resolution	0.005 °	
Velocity accuracy*	0.04 km/h RMS	
Lateral velocity*	0.2 % RMS	
GPS outage position error*	after 10 / 30 / 60 sec: 0.4 / 5.0 / 40.0 m RMS	
GPS outage velocity error*	after 10 / 30 / 60 sec: 0.06 / 0.5 / 1.8 m/sec RMS	
GPS outage pitch / roll angle error*	after 10 / 30 / 60 sec: 0.05 / 0.15 / 0.35 ° RMS	
GPS outage heading angle error*	after 10 / 30 / 60 sec: 0.1 / 0.3 / 0.5 ° RMS	
Axis misalignment	± 0.05 °	
Initial heading alignment	with internal GPS receiver or by manual input	
Data update rate / calculation latency	50 – 400 HZ (1000 Hz optional) / 1ms	
INTERFACES		
Ethernet	1 x Gbit, for data output, configuration and firmware update, driving robot data output, optional for relative data calculation (e.g. range) and DGPS routing, input/output	
CAN	1 x CAN 2b, 1 Mbit, for data output	
СОМ	1 x RS232	
Signal inputs	up to 4 x TTL, isolated (e.g. for light barrier or brake trigger)	
Signal outputs	up to 4 x TTL, isolated (e.g. for synchronization and error indication)	
DGPS correction data input	1 for NTRIP-/ RF Modem	
Connector type for digital signals and power	7 x LEMO-connector (standard version)	
	1 x MIL-connector (single connector version)	
GNSS antenna input	1 x SMA ( 2 x SMA optional)	
MISCELLANEOUS		
Power supply	12 VDC nominal (9-32 VDC), 14 Watt typ.	
Dimensions (W x L x H)	130 x 177 x 47 mm (housed version)	
	125 x 100 x 30 mm (unhoused OEM version)	
Weight	1.50 kg (housed version)	
	0.3 kg (unhoused version)	
Protection class	IP 67 (housed version)	
Temperature range	-20 to +60 °C (housed version)	

 $^{\star}$  typical values according to internal test standards with settled Kalman filter

## **Technical Data**

GYROS	
Quantity / Type	3 MEMS gyros
Measurement range	± 450 °/s
Resolution roll / pitch / yaw	3 x 10 <sup>-7</sup> °/s
Bias variation over temperature range typically	± 0.0025 °/s / °C (1 σ)
In-run-bias typically	6 °/h (1 σ)
Gyro noise typically	0.3 °/ <b>√</b> h
Scale factor	±1%
Sensor bandwidth	330 Hz
ACCELEROMETERS	
Quantity / Type	3 MEMS accelerometers
Measurement range	$\pm$ 5 g, optional $\pm$ 10 g, option
Measurement accuracy (without Kalman filter corrections)	better than 5 mg
In-run-bias typically	32 μg (1 σ)
Scale factor	± 0.5 %
Digitized measurement resolution	3.8 x 10 <sup>-9</sup> g
Sensor bandwidth	330 Hz
GNSS	
Position accuracy	0.01 / 0.2 / 0.4 / 0.6 / 1.2 / 1 on license model and DGPS
Data update rate	up to 50 msec (internally inte to 2.5 msec, optionally 1 ms
WAAS/EGNOS-DGPS corrections	via satellite
DGPS corrections	via NTRIP-/ RF Modem or Et
RTK2-DGPS	via NTRIP-/ RF Modem or Et
Satellite tracking	GPS single antenna (standar
GLONASS / Galileo / BeiDou / L-Band	optional
Dual antenna version	optional

# **Auxiliary Accessories**

- ▲ Signal-In cable (for brake/light barrier trigger)
- ▲ Signal-Out cable (for synchronization and error signals)
- ▲ NTRIP-DGPS-Box 4 with accessories for RTK network connection
- ▲ RF modem set with accessories for DGPS correction data reception from local GPS Base Station
- ▲ WiFi Kit for remote access
- ▲ Mounting kit with 4 high power magnets

 All new functions of ADMA (refer to page 6-7) are also available for ADMA-Slim 2 Dnal 18 g 1.5 m (depending S corrections) rerpolated from 20 sec) Ethernet (optional) Ethernet (optional) ard)

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