

### The **FIRST POWER-IMU** for Mobile **POWER-Machines**

#### **NEW!** With an extended range of functions

Our configurable sensor measuring unit GEMAC Motus® enables 6-axis motion detection on Mobile POWER-Machines, such as **construction machinery, agricultural and forestry machinery, cranes and lifting technology**, as well as **ships**. Our proprietary **sensor fusion algorithm** performs high-precision orientation calculation, supported by sensor fusion filters that suppress external accelerations. The combination and calculation of the six measured values mean that only one measuring system needs to be integrated for a wide range of requirements.

# The accuracy of the inclination measurement includes a compensated cross-sensitivity\* and is independent of the local gravity field due to the 3D measurement.

GEMAC Motus<sup>®</sup> stands for the highest performance in the highprecision recording and digitization of movements with the aim of guaranteeing the greatest possible safety when using Mobile POWER-Machines. The design and functionality also ensure maximum durability and economy.





ZGEMAC

GEMAC Motus®XC XC6MZ360-O Order No.: PR-27116-30 Serial No.: 27116-30/000001 7.5...36 VDC • IP6K7/IP6K9K Interface: CANopen GEMAC Chemiltz GmbH

POWER

## GEMAC Motus® variants

- → Recording of inclination: GEMAC Motus<sup>®</sup> NB and NC
- → Recording of acceleration and rotation rate: GEMAC Motus<sup>®</sup> IB
- → Recording of inclination, acceleration and rotation rate: GEMAC Motus<sup>®</sup> XB and XC



	NB	NC	IB		
General parameters	Inclin	ation	Accelerometer	Gyroscope	
Measurement range	360%	/±90°	±8g	±250 °/s	
Resolution	0.01°		0.244 mg	0.00875 °/s	
Temperature coefficient	±0.01°/K	±0.0016°/K	0.2 mg/K	0.005°/s/K	
Static accuracy*	±0.3°	±0.1°			
Dynamic accuracy*	±0.5°	±0.25°			
In run bias stability				2.5°/h	
Angle Random Walk (ARW)				0.1°/√h	
Interface	U, I, CAN, CANC	pen, SAE J1939	CAN, CANopen, SAE J1939		

Variants	ХВ			ХС		
General parameters	Inclination	Accelerometer	Gyroscope	Inclination	Accelerometer	Gyroscope
Measurement range	360°	±8g	±250 °/s	360°	±8g	±250 %
Resolution	0.01°	0.244 mg	0.00875°/s	0.01°	0.244 mg	0.00875°/s
Temperature coefficient	±0.005°/K	0.2 mg/K	0.005°/s/K	±0.0016 °/K	0.02 mg/K	0.005 °/s/K
Static accuracy*	±0.3°			±0.1°		
Dynamic accuracy*	±0.5°			±0.25°		
In run bias stability			2.5 °/h			2.5 °/h
Angle Random Walk (ARW)			0.1°/√h			0.1°/√h
Interface	CAN, CANopen, SAE J1939			CAN, CANopen, SAE J1939		

#### **NEW!** With an extended range of functions

- → Automatic configuration of the mounting position
- → Flexible zero point adjustment
- → Expert mode with extended setting options

#### Available interfaces:

- → CAN 2.0 A and B (11- and 29-Bit-ID) according ISO 11898-2
- → CANopen according CiA DS-301, profile according CiA DSP-410
- → SAE J1939, configurable process data

#### Mechanical parameters:

**Connector:** 1 or 2 sensor connectors 5-pole M12, A-coded **Degree of protection:** IP6K7/IP6K9K, Operating temperature: -40 °C to +85 °C **Dimensions and weight:** 114 mm x 66 mm x 30 mm, approx. 330 g **Housing material:** zinc die casting, nickel plated \* incl. compensated cross sensitivity

- ➔ Configuration of the sensor fusion
- ➔ Configuration of the output data with SAE J1939
- CANopen autostart
- → Starter kit (including programming adapter, cables and PC software)
- → Analog: Current (4 ... 20 mA), Voltage (0 ... 10 V)

#### **Electrical parameters:**

**Supply Voltage:** 10V to 36V (in some cases from 7.5V) **Current consumption at 24V:** approx. 12 mA (digital), max. 70 mA (analog)

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