GEMAC Motus[®] Product overview

| GEMAC Motus [®] GREENLINE | GEMAC Motus® BLACKLINE | GEMAC Motus [®] |
|------------------------------------|------------------------|--------------------------|
| | | |
| | | |

| | | accuracy ¹ | GEMAC Motus [®] GREENLINE | GEMAC Motus [®] BLACKLINE | GEMAC Motus® |
|-------|----------|-----------------------|------------------------------------|------------------------------------|--------------|
| | Е | static | ±0.1° to ±0.5° | - | - |
| Class | economic | dynamic | ±0.8° | - | - |
| nce (| в | static | - | ±0.3° | ±0.3° |
| orma | basic | dynamic | - | ±0.5° | ±0.5° |
| Perfo | с | static | - | ±0.1° | ±0.1° |
| | classic | dynamic | - | ±0.5° | ±0.25° |

Product variants of GEMAC Motus®

| X Inertial measure- ment unit (IMU) | | | | | | | | | | | | | | IB |
|---|------------------|---------|----------|------------------|----------|-----------|-------------|--------|-------------|-------------|-----------|-------------|----------|----------|
| N Inclination sensor dynamic | | | | | ND | | NC | | XE | ХВ | XB | ХС | ХС | |
| S Inclination sensor static | SE | SB | SC | NE | NB | ND | NC | NC | | | | | | |
| Inclination, Accelerome | ter, Gyros | scope | | | | | | | | | | | | |
| Measurement range Inclination ² | | | | | | ±90° | °/ ±180° (3 | 60°) | | | | | | - |
| Measurement range Accelerometer | - | - | - | - | - | - | - | - | ±2g | ±8g | ±8g | ±8g | ±8g | ±8g |
| Measurement range Gyroscope | - | - | - | - | - | - | - | - | ±250 % | ±250 % | ±250 % | ±250 % | ±250 % | ±250 % |
| Static accuracy ¹ | ±0.1° to 0.5° | ±0.3° | ±0.1° | ±0.1° to 0.5° | ±0.3° | ±0.3° | ±0.1° | ±0.1° | ±0.5° | ±0.3° | ±0.3° | ±0.1° | ±0.1° | - |
| Dynamic accuracy ¹ | - | - | - | ±0.8° | ±0.5° | ±0.5° | ±0.5° | ±0.25° | ±0.8° | ±0.5° | ±0.5° | ±0.5° | ±0.25° | - |
| In run bias stability | - | - | - | - | - | - | - | - | 10°/h | 5 °/h | 2.5 %h | 5 °/h | 2.5 %h | 2.5 %h |
| Angle Random Walk (ARW) | - | - | - | - | - | - | - | - | 0.4 °/√h | 0.2 °∕√h | 0.1 °/√h | 0.2 °∕√h | 0.1 °/√h | 0.1 °/√h |
| Interface | CA | N, CANO | pen, SAE | J1939, Cur | rent 420 |) mA, Vol | tage 010 | \vee | | CAN | l, CANope | en, SAE JI | 939 | |

 1 incl. compensated cross sensitivity 2 up to 2 measuring axes with configurable orientation







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GEMAC Motus® Order overview

Performance Class - E economic

| Stat. accuracy | ±0.1° to ±0.5° | | | | | |
|----------------|----------------|----------------|----------------|----------------|--|--|
| Dyn. accuracy | | | | | | |
| Product line | | GREE | NLINE | | | |
| Specification | 4-hole | variant | 2-hole variant | | | |
| Meas. range | +/- 90° | ±180° (360°) | +/- 90° | ±180° (360°) | | |
| Axis | 2D | 1D | 2D | 1D | | |
| CAN | PR-2803 | 8-00-00 | PR-2802 | 8-00-00 | | |
| CANopen | PR-2813 | 8-00-00 | PR-2812 | 8-00-00 | | |
| SAE J1939 | PR-2873 | 8-00-00 | PR-2872 | 8-00-00 | | |
| Current | PR-28438-00-00 | PR-28437-00-00 | PR-28428-00-00 | PR-28427-00-00 | | |
| Voltage | PR-28538-00-00 | PR-28537-00-00 | PR-28528-00-00 | PR-28527-00-00 | | |

| Stat. accuracy | ±0.1° to ±0.5° | | | | | |
|----------------|----------------|----------------|----------------|----------------|--|--|
| Dyn. accuracy | | ±0 | .8° | | | |
| Product line | | GREE | NLINE | | | |
| Specification | 4-hole | variant | 2-hole variant | | | |
| Meas. range | +/- 90° | ±180° (360°) | +/- 90° | ±180° (360°) | | |
| Axis | 2D | 1D | 2D | 1D | | |
| CAN | PR-2803 | 4-00-00 | PR-2802 | 4-00-00 | | |
| CANopen | PR-2813 | 4-00-00 | PR-2812 | 4-00-00 | | |
| SAE J1939 | PR-2873 | 4-00-00 | PR-2872 | 4-00-00 | | |
| Current | PR-28434-00-00 | PR-28430-00-00 | PR-28424-00-00 | PR-28420-00-00 | | |
| Voltage | PR-28534-00-00 | PR-28530-00-00 | PR-28524-00-00 | PR-28520-00-00 | | |

±0.5° Stat. accuracy Dyn. accuracy ±0.8° GREENLINE Specification 4-hole variant 2-hole variant +/- 90° ±180° (360°) +/- 90° ±180° (360°) Meas. range PR-28036-00-00 PR-28026-00-00 PR-28136-00-00 PR-28126-00-00 SAE J1939 PR-28736-00-00 PR-28726-00-00

Inclination sensor dynamic

Inclination sensor static

measurement unit / IMU X/I Inertial

Product line CAN CANopen

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GEMAC Motus® Order overview

Performance Class - B basic

Performance Class - C classic

| | Stat. accuracy | ±0.3° |
|------|----------------|-----------------|
| | Dyn. accuracy | - |
| tic | Product line | BLACKLINE |
| sta | Specification | |
| lsor | Meas. range | to ±180° (360°) |
| Ser | Axis | 1D/2D |
| tion | CAN | PR-26048-30-00 |
| lina | CANopen | PR-26148-30-00 |
| lno | SAE J1939 | PR-26748-30-00 |
| | Current | PR-26448-00-00 |
| | Voltage | PR-26548-00-00 |

| ±0.1° |
|-----------------|
| - |
| BLACKLINE |
| |
| to ±180° (360°) |
| 1D/2D |
| PR-27048-30-00 |
| PR-27148-30-00 |
| PR-27748-30-00 |
| PR-27448-00-00 |
| PR-27548-00-00 |

| | Stat. accuracy | ±0.3° | ±0.3° | ±0.3° | ±0.1° | ±0.1° | ±0.1° |
|-------------|----------------|-----------------|---------------------|------------------|-----------------|-----------------|--------------|
| | Dyn. accuracy | ±0.5° | ±0.5° | ±0.5° | ±0.5° | ±0.25° | ±0.25° |
| | Product line | BLACKLINE | GEMAC Motus® | GEMAC Motus® | BLACKLINE | GEMAC Motus® | GEMAC Motus® |
| JAD | Specification | | | | | | |
| D D D | Meas. range | to ±180° (360°) | +/- 90° | ±180° (360°) | to ±180° (360°) | +/- 90° | ±180° (360°) |
| Sens | Axis | 1D/2D | 2D | 1D | 1D/2D | 2D | 1D |
| | CAN | PR-26044-30-00 | PR-26014-30 | PR-26010-30 | PR-27044-30-00 | PR-27014-30 | PR-27010-30 |
| nat | CANopen | PR-26144-30-00 | PR-26114-30 | PR-26110-30 | PR-27144-30-00 | PR-27114-30 | PR-27110-30 |
| | SAE J1939 | PR-26744-30-00 | PR-26714-30 | PR-26710-30 | PR-27744-30-00 | PR-27714-30 | PR-27710-30 |
| | Current | PR-26444-00-00 | PR-26414-00 | PR-26410-00 | PR-27444-00-00 | PR-27414-00 | PR-27410-00 |
| | Voltage | PR-26544-00-00 | PR-26514-00 | PR-26510-00 | PR-27544-00-00 | PR-27514-00 | PR-27510-00 |
| | | | | | | | |
| 5 | Stat. accuracy | ±0.3° | - | ±0.3° | ±0.1° | ±0.1° | |
| Σ | Dyn. accuracy | ±0.5° | - | ±0.5° | ±0.5° | ±0.25° | |
| Ĕ | Product line | BLACKLINE | GEMAC Motus® | GEMAC Motus® | BLACKLINE | GEMAC Motus® | |
| | Specification | | without inclination | with inclination | | | |
| Be | Meas. range | to ±180° (360°) | to ±180° (360°) | to ±180° (360°) | to ±180° (360°) | to ±180° (360°) | |
| sure | CAN | PR-26046-30-00 | PR-26015-30 | PR-26016-30 | PR-27046-30-00 | PR-27016-30 | |
| 60 | CANopen | PR-26146-30-00 | PR-26115-30 | PR-26116-30 | PR-27146-30-00 | PR-27116-30 | |

PR-26716-30

PR-27746-30-00

PR-27716-30

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SAE J1939

PR-26746-30-00

PR-26715-30



GEMAC Motus[®] Product overview

GEMAC Motus® GREENLINE



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| Product line | GEMAC Motus® GREENLINE 4-hole variant | GEMAC Motus® GREENLINE 2-hole variant |
|---------------------|--|--|
| Dimensions | 62 x 32.3 x 18.7 mm (without cable) | 43.5 x 76.3 x 18.7 mm (without cable) |
| Weight | approx. 30 g (without cable) | approx. 30 g (without cable) |
| Housing material | plastic (PA) | plastic (PA) |
| | | |

Dimensions of all housing variants

| Product line | GEMAC Motus® GREENLINE 2-hole variant | GEMAC Motus® GREENLINE 4-hole variant | GEMAC Motus® BLACKLINE | GEMAC Motus® |
|---------------------|--|--|---------------------------|---------------------------------|
| Dimensions | 43.5 x 76.3 x 18.7 mm (without cable) | 62 x 32.3 x 18.7 mm (without cable) | 121 mm x 66 mm x 30 mm | 114 mm x 66 mm x 30 mm |
| Weight | approx. 30 g (without cable) | approx. 30 g (without cable) | approx. 200 g | approx. 330 g |
| Housing material | plastic (PA) | plastic (PA) | plastic (PA) | zinc die casting, nickel plated |



GEMAC Motus® Product overview

GEMAC Motus® BLACKLINE

GEMAC Motus®





| Product line | GEMAC Motus [®] BLACKLINE | GEMAC Motus [®] | | |
|---------------------|------------------------------------|---------------------------------|--|--|
| Dimensions | 121 mm x 66 mm x 30 mm | 114 mm x 66 mm x 30 mm | | |
| Weight | approx. 200 g | approx. 330 g | | |
| Housing material | plastic (PA) | zinc die casting, nickel plated | | |
| analog | | | | |
| digital | | | | |



PRÉLIMINARY

GEMAC Motus® GREENLINE

GEMAC Motus® GREENLINE

POWER

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The **FIRST** POWER-IMU for Mobile POWER-Machines

GEMAC Motus® *CREENLINE* with its slim design puts the focus above all on flexibility and price. With the two standard housing variants available for 2- or 4-point mounting, the user gains more independence from the existing hole patterns on the mobile machine. Customerspecific mounting variants are possible on request.

GEMAC Motus® GREENLINE SE2XP090-U

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With a static accuracy of ±0.5° the **GEMAC Motus**[®] *GREENLINE* offers a wide range of applications, e.g. in **agriculture and forestry, crane and lifting technology, industrial trucks** and **industrial automation**.

Other variants of the **GEMAC Motus®** *GREENLINE* are also capable of measuring inclination in dynamic processes via a sensor fusion algorithm developed in-house by GEMAC.

The **GEMAC Motus®** *GREENLINE* portfolio is rounded off by IMU cost effective solutions, which, in addition to inclination, also measure acceleration and rotation rate in all 3 axes via the digital interface.

The sensor measuring units can be parameterized very conveniently via a programming kit and enable the user to optimally match his applications with the sensors to the existing technical requirements.





GEMAC Motus® GREENLINE variants

- → Recording of static inclination: GEMAC Motus[®] GREENLINE SE
- → Recording of static and dynamic inclination: GEMAC Motus[®] GREENLINE NE
- → Recording of inclination (static and dynamic), acceleration and rotation rate: GEMAC Motus[®] GREENLINE XE



| Variants | SE | NE | | | |
|-------------------------------|--|--------------------------------|--|--|--|
| General parameters | Inclination static | Inclination static and dynamic | | | |
| Measurement range digital | ±90°/ ±180° (360°) ² | ±90°/ ±180° (360°) ² | | | |
| Measurement range analog | ±5° to ±180° (360°) ² | ±5° to ±180° (360°) ² | | | |
| Resolution digital | 0.01° | 0.01° | | | |
| Resolution analog | 0.01° to 0.1° | 0.01° to 0.1° | | | |
| Temperature coefficient | ±0.02 °/K | ±0.02 °/K | | | |
| Static accuracy ¹ | ±0.1° to ±0.5° | ±0.1° to ±0.5° | | | |
| Dynamic accuracy ¹ | | ±0.8° | | | |
| Interface | CAN, CANopen, SAE J1939, Current 420 mA, Voltage 010 V | | | | |

Note:

Resolution and accuracy depend on the measuring range of the sensor. With a lower measuring range, a higher resolution and accuracy are achieved (with default settings, see minimum values in table). The number of measuring axes (max. 2), their axis assignment, measuring range and range of the analog output are preconfigured in the factory or can be parameterized by the customer.

| Variants | | XE | |
|-------------------------------|---------------------------------|-------------------------|-----------|
| General parameters | Inclination | Accelerometer | Gyroscope |
| Measurement range | ±90°/ ±180° (360°) ² | ±2g | ±250 °/s |
| Resolution | 0.01° | 0.488 mg | 0.035 %s |
| Temperature coefficient | ±0.02°/K | 0.4 mg/K | 0.02°/s/K |
| Static accuracy ¹ | ±0.5° | | |
| Dynamic accuracy ¹ | ±0.8° | | |
| In run bias stability | | | 10°/h |
| Angle Random Walk (ARW) | | | 0.4 °/√h |
| Interface | | CAN, CANopen, SAE J1939 | |

Available interfaces:

- → CAN 2.0 A and B (11- and 29-Bit-ID) according ISO 11898-2
- → CANopen according CiA DS-301, profile according CiA DSP-410
- → SAE J1939, configurable process data
- → Starter kit (including programming adapter, cables and PC software)

Mechanical parameters:

Connector: cable (0.2 m) with sensor connector M12 5-pole, A-coded (customer-specific connection variants on request) **Degree of protection:** IP6K7/IP6K9K, Operating temperature: -40°C to +80°C

Dimensions and weight: 4-hole variant 62 x 32.3 x 18.7 mm (without cable), 2-hole variant 43.5 x 76.3 x 18.7 mm (without cable), approx. 30 g without cable **Housing material:** plastic (PA)

→ Analog: Current (4...20 mA), Voltage (0...10 V), customized values on request

¹ incl. compensated cross sensitivity ² up to 2 measuring axes with configurable orientation

→ Output linearized or non-linearized (configurable)

Electrical parameters:

Supply Voltage: 11 V to 30 V (in some cases from 7.5 V) **Current consumption at 24 V:** approx. 12 mA (digital), max. 70 mA (analog)

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GEMAC Motus® BLACKLINE

GEMAC Motus® BLACKLINE

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POWER

The FIRST POWER-IMU for Mobile POWER-Machines

GEMAC Motus® BLACKLINE expands the portfolio of the GEMAC Motus® sensor generation with additional high-precision sensor variants.

The configurable sensor measuring unit GEMAC Motus[®] enables 6-axis motion detection on Mobile POWER-Machines, such as **construction machinery, agricultural and forestry machinery, cranes and lifting technology**, as well as **ships**.

GEMAC Motus® BLACKLINE also offers cost-effective variants in plastic housing and different accuracy types.

Our in-house developed sensor fusion algorithm with the **"Enhanced Kalman Filter"** specially optimized for motion detection takes over the highly accurate orientation calculation and is even more robust. It enables the correction of nonlinear disturbances and thus even better damping of external accelerations or vibrations.

The accuracy of the inclination measurement includes a compensated cross-sensitivity and is independent of the local gravity field due to the 3D measurement.

- Automatic adaptation of the filter parameters according to the motion state of the sensor
- Improved offset correction of the gyroscope
- Increased user-friendliness through simplification of sensor configuration





GEMAC Motus® BLACKLINE variants

- → Recording of static inclination: GEMAC Motus[®] BLACKLINE SB and SC
- → Recording of static and dynamic inclination: GEMAC Motus[®] BLACKLINE NB and NC
- → Recording of inclination (static and dynamic), acceleration and rotation rate:
 GEMAC Motus[®] BLACKLINE XB and XC



| | SB | SC | NB | NC | |
|-------------------------------|--|------------|--------------------------------|------------|--|
| General parameters | Inclination static | | Inclination static and dynamic | | |
| Measurement range | ±90°/ ±180° (360°) ² | | ±90°/ ±180° (360°) ² | | |
| Resolution | 0.0 | 01° | 0.01° | | |
| Temperature coefficient | ±0.01°/K | ±0.0016°/K | ±0.01°/K | ±0.0016°/K | |
| Static accuracy ¹ | ±0.3° | ±0.1° | ±0.3° | ±0.1° | |
| Dynamic accuracy ¹ | - | - | ±0.5° | ±0.5° | |
| Interface | CAN, CANopen, SAE J1939, Current 420 mA, Voltage 010 V | | | | |

| Variants | ХВ | | | хс | | |
|-------------------------------|------------------------------------|---------------|------------|-------------------------|---------------|------------|
| General parameters | Inclination | Accelerometer | Gyroscope | Inclination | Accelerometer | Gyroscope |
| Measurement range | ±90°/ ±180° (360°) ² | ±8g | ±250 % | ±90°/ ±180° (360°) ² | ±8g | ±250°/s |
| Resolution | 0.01° | 0.244 mg | 0.00875°/s | 0.01° | 0.244 mg | 0.00875°/s |
| Temperature coefficient | ±0.01°/K | 0.2 mg/K | 0.01°/s/K | ±0.0016°/K | 0.02 mg/K | 0.01°/s/K |
| Static accuracy ¹ | ±0.3° | | | ±0.1° | | |
| Dynamic accuracy ¹ | ±0.5° | | | ±0.5° | | |
| In run bias stability | | | 5°/h | | | 5°/h |
| Angle Random Walk (ARW) | | | 0.2°/√h | | | 0.2°∕√h |
| Interface | CAN, CANopen, SAE J1939 | | | | | |

¹incl. compensated cross sensitivity ²up to 2 measuring axes with configurable orientation

Range of functions:

- → Automatic adaptation of the filter parameters according to the motion state of the sensor
- → Improved offset correction of the gyroscope
- More user-friendliness through simplification of sensor configuration
- Automatic configuration of the mounting position
- → Flexible zero point adjustment
- → Expert mode with advanced setting options
- → Individual configuration of the sensor fusion

Mechanical parameters:

Connector: 1 or 2 sensor connectors M12 5-pole, A-coded **Degree of protection:** IP6K7/IP6K9K, Operating temperature: -40 °C to +85 °C **Dimensions and weight:** 121 mm x 66 mm x 30 mm, approx. 200 g

Housing material: plastic (PA)

Available interfaces:

- → CAN 2.0 A and B (11- and 29-Bit-ID) according ISO 11898-2
- → CANopen according CiA DS-301, profile according CiA DSP-410
- → SAE J1939, configurable process data
- → Analog: Current (4...20 mA), Voltage (0...10 V)
- Starter kit (including programming adapter, cables and PC software)

Electrical parameters:

Supply Voltage: 10V to 36V (in some cases from 7.5V) Current consumption at 24 V: approx. 12 mA (digital), max. 70 mA (analog)

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ZGEMAC

GEMAC Motus[®]XC XC6MZ360-O Order No.: PR-27116-30 Serial No.: 27116-30/000001 7.5...36 VDC • IP6K7/IP6K9K I/F: CANopen

POWER

The **FIRST POWER-IMU** for Mobile **POWER-Machines**

NEW! With an extended range of functions

Our configurable sensor measuring unit GEMAC Motus® enables 6-axis motion detection on Mobile POWER-Machines, such as **construction machinery, agricultural and forestry machinery, cranes and lifting technology**, as well as **ships**. Our proprietary **sensor fusion algorithm** performs high-precision orientation calculation, supported by sensor fusion filters that suppress external accelerations. The combination and calculation of the six measured values mean that only one measuring system needs to be integrated for a wide range of requirements.

The accuracy of the inclination measurement includes a compensated cross-sensitivity and is independent of the local gravity field due to the 3D measurement.

GEMAC Motus[®] stands for the highest performance in the highprecision recording and digitization of movements with the aim of guaranteeing the greatest possible safety when using Mobile POWER-Machines. The design and functionality also ensure maximum durability and economy.



GEMAC Motus® variants

- → Recording of inclination: GEMAC Motus[®] NB and NC
- → Recording of acceleration and rotation rate: GEMAC Motus[®] IB
- → Recording of inclination, acceleration and rotation rate: GEMAC Motus[®] XB und XC



| Variants | NB | NC | ll. | 8 | |
|-------------------------------|---------------------|------------------------|-------------------------|-------------|--|
| General parameters | Inclination | | Accelerometer | Gyroscope | |
| Measurement range | ±90°/±180° (360°) ² | | ±8g | ±250 % | |
| Resolution | 0.01° | | 0.244 mg | 0.00875°/s | |
| Temperature coefficient | ±0.01°/K | ±0.0016 °/K | 0.2 mg/K | 0.005 °/s/K | |
| Static accuracy ¹ | ±0.3° | ±0.1° | | | |
| Dynamic accuracy ¹ | ±0.5° | ±0.25° | | | |
| In run bias stability | | | | 2.5°/h | |
| Angle Random Walk (ARW) | | | | 0.1°/√h | |
| Interface | CAN, CANopen, SAE J | 1939, Current, Voltage | CAN, CANopen, SAE J1939 | | |

| Variants | ХВ | | | ХС | | |
|-------------------------------|------------------------------------|---------------|-------------------------|-------------------------|---------------|-------------|
| General parameters | Inclination | Accelerometer | Gyroscope | Inclination | Accelerometer | Gyroscope |
| Measurement range | ±90°/ ±180° (360°) ² | ±8g | ±250 % | ±90°/ ±180° (360°) ² | ±8g | ±250°/s |
| Resolution | 0.01° | 0.244 mg | 0.00875°/s | 0.01° | 0.244 mg | 0.00875°/s |
| Temperature coefficient | ±0.005°/K | 0.2 mg/K | 0.005°/s/K | ±0.0016°/K | 0.02 mg/K | 0.005 °/s/K |
| Static accuracy ¹ | ±0.3° | | | ±0.1° | | |
| Dynamic accuracy ¹ | ±0.5° | | | ±0.25° | | |
| In run bias stability | | | 2.5 °/h | | | 2.5 °/h |
| Angle Random Walk (ARW) | | | 0.1°/√h | | | 0.1 °/√h |
| Interface | CAN, CANopen, SAE J1939 | | CAN, CANopen, SAE J1939 | | | |

NEW! With an extended range of functions

- → Automatic configuration of the mounting position
- → Flexible zero point adjustment
- → Expert mode with extended setting options

Available interfaces:

- → CAN 2.0 A and B (11- and 29-Bit-ID) according ISO 11898-2
- → CANopen according CiA DS-301, profile according CiA DSP-410
- → SAE J1939, configurable process data

Mechanical parameters:

Connector: 1 or 2 sensor connectors M12 5-pole, A-coded **Degree of protection:** IP6K7/IP6K9K, Operating temperature: -40 °C to +85 °C **Dimensions and weight:** 114 mm x 66 mm x 30 mm, approx. 330 g **Housing material:** zinc die casting, nickel plated $^{\rm 1}$ incl. compensated cross sensitivity $^{\rm 2}$ up to 2 measuring axes with configurable orientation

- → Configuration of the sensor fusion
- → Configuration of the output data with SAE J1939
- CANopen autostart
- → Starter kit (including programming adapter, cables and PC software)
- → Analog: Current (4 ... 20 mA), Voltage (0 ... 10 V)

Electrical parameters:

Supply Voltage: 10V to 36V (in some cases from 7.5V) **Current consumption at 24V:** approx. 12 mA (digital), max. 70 mA (analog)

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